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TECHNICAL REPORT NO. 2

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DEPARTMENT OF STATISTICS
STANFORD UNIVERSITY
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A REVIEW AND SOME EXTENSIONS OF
TAKEMURA'S GENERALIZATIONS OF COCHRAN'S THEOREM

by

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This is a review of the Stanford Technical Report No.44 by Akimichi Takemura "On Generalizations of Cochran's Theorem and Projection Matrices" (August 1980). A number of extensions are also presented. In Section 1 we review the notions of direct sum of matrices and of vector spaces, and show the equivalence of several different definitions. We also examine Takemura's "independent" vector spaces and find that they coincide with the "disjoint" vector spaces considered by Rao and Yanai (1979). The connection of this concept with rank additivity is explored in Section 2. In Sections 3 and 4 we elaborate and extend several results of Takemura's on rank additivity and r -potent matrices and matrix polynomials. These results build on those given by Anderson and Styan (1980).

1. Direct Sums, Virtual Disjointness and Independence.

Let the vector spaces U_1, \dots, U_k be subspaces of a vector space X of $m \times 1$ column vectors and let the matrices A_1, \dots, A_k be defined by

$$(1.1) \quad C(A_i) = U_i, \quad i = 1, \dots, k,$$

where $C(\cdot)$ denotes column space (range). The matrices A_1, \dots, A_k all have the same number of rows: m . Let A_i be $m \times n_i$ and write $n = \sum_{i=1}^k n_i$. Let

$$(1.2) \quad D = \begin{pmatrix} A_1 & & \\ & \ddots & \\ & & A_k \end{pmatrix}$$

be the $km \times n$ block-diagonal matrix of the A_i 's.

The matrix D is defined as the *direct sum of the matrices* A_1, \dots, A_k (cf. Marcus and Minc, 1964, pages 5-6). This definition is also valid when the A_i do not all have the same number of rows. We may write

$$(1.3) \quad D = A_1 \oplus \dots \oplus A_k.$$

Let the $km \times m$ partitioned matrix

$$(1.4) \quad K = (I_m, \dots, I_m)',$$

cf. Anderson and Styan (1980, p.11). Then the $m \times n$ partitioned matrix

$$(1.5) \quad B = (A_1, \dots, A_k) = K'D$$

spans the union of the vector spaces U_1, \dots, U_k ,

$$(1.6) \quad U = U_1 \cup \dots \cup U_k = C(A_1, \dots, A_k) = C(B).$$

We define the matrices A_1, \dots, A_k and the vector spaces U_1, \dots, U_k to be *mutually virtually disjoint* whenever

$$(1.7) \quad r(A_1, \dots, A_k) = \sum_1^k r(A_i),$$

where $r(\cdot)$ denotes rank, cf. Styan (1981). We may write (1.7) as

$$(1.8) \quad r(K'D) = r(D)$$

or equivalently as

$$(1.9) \quad \dim(U_1 \cup \dots \cup U_k) = \sum_1^k \dim U_i,$$

where $\dim(\cdot)$ denotes dimension of the vector space.

When the vector spaces U_1, \dots, U_k are *mutually virtually disjoint* then we define their union as the *direct sum of the vector spaces* U_1, \dots, U_k , and we write

$$(1.10) \quad U_1 \oplus \dots \oplus U_k = U_1 \cup \dots \cup U_k = C(A_1, \dots, A_k) = C(K'D).$$

Rao and Mitra (1971, page 3, lines 5-6) define the two vector spaces U_i and U_j to be *virtually disjoint* whenever their intersection

$$(1.11) \quad U_i \cap U_j = \{0\},$$

the null vector only, or equivalently

$$(1.12) \quad r(A_i, A_j) = r(A_i) + r(A_j),$$

cf. Marsaglia and Styan (1974, page 272 (2.19)). Clearly (1.7) \Rightarrow (1.12) for all $i \neq j$ and so (1.9) \Rightarrow (1.11) for all $i \neq j$. The converse, however, holds in general only for $k = 2$; if $k = 3$ and

$$(1.13) \quad A_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad A_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad A_3 = \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$

then (1.12) holds for all $i \neq j$ but (1.7) does not.

Rao and Yanai (1979, page 2, section 2, lines 4-5) use (1.11) to define U_i and U_j "disjoint" and then (page 2, Definition 1) define U_1, \dots, U_k as "disjoint" whenever

$$(1.14) \quad u \in U_1 \cup \dots \cup U_k = C(A_1, \dots, A_k) = C(B) = C(K'D)$$

has the unique representation

$$(1.15) \quad u = \sum_1^k u_i; \quad u_i \in U_i, \quad i = 1, \dots, k.$$

Rao (1973, page 11 (vii)) uses this as a definition of "direct sum"; see also Takemura (1980, page 2, lines -6 and -7).

To see that (1.15) follows from (1.7) we write

$$(1.16) \quad u = Bx^{(1)} = K'Dx^{(1)} = Bx^{(2)} = K'Dx^{(2)}.$$

Then

$$(1.17) \quad K'Dx^{(1)} = K'Dx^{(2)} \Rightarrow Dx^{(1)} = Dx^{(2)},$$

which follows at once from (1.8) and the left-hand rank cancellation rule (Anderson and Styan (1980, page 12, Lemma 2.2)).

A connection between the definitions of matrix direct sum and vector-space direct sum is provided by the equality of the row spaces of $l \times n$ row vectors

$$(1.18) \quad R(K'D) = R(D)$$

or equivalently

$$(1.19) \quad R(A_1, \dots, A_k) = R \begin{pmatrix} A_1 \\ \vdots \\ A_k \end{pmatrix} = R(A_1 \oplus \dots \oplus A_k).$$

This follows from (1.8) since $R(K'D) \subseteq R(D)$ always holds.

There seems to be no direct connection, however, between the vector-space direct sum $U_1 \oplus \dots \oplus U_k = C(A_1, \dots, A_k)$ of $m \times 1$ vectors and the column space of $km \times 1$ vectors of the matrix direct sum $C(A_1 \oplus \dots \oplus A_k)$.

The "definition" given by Takemura (1980, page 2, paragraph 3, line 3) of U_1, \dots, U_k being (linearly) independent is that if

$$(1.20) \quad u_i \in U_i, i = 1, \dots, k \text{ and } \sum_{i=1}^k u_i = 0 \text{ then } u_i = 0, i = 1, \dots, k.$$

This is given by Rao and Yanai (1979, page 4) as the "result" (1): that if A_1, \dots, A_k are "disjoint" then

$$(1.21) \quad \sum_{i=1}^k A_i x_i = 0 \iff A_i x_i = 0, \quad i = 1, \dots, k.$$

We may write (1.21) as

$$(1.22) \quad K'Dx = 0 \iff Dx = 0,$$

which follows at once from (1.8) and the left-hand rank cancellation rule (cf. Anderson and Styan, 1980, page 12, Lemma 2.2).

Rao and Yanai (1979, page 5, Theorem 1) prove that if

$$(1.23) \quad Y = \begin{pmatrix} Y_1 \\ \vdots \\ Y_k \end{pmatrix} = B^- = (A_1, \dots, A_k)^-$$

is a generalized inverse of B then

$$(1.24) \quad A_i Y_i A_i = A_i, \quad i = 1, \dots, k, \quad \text{and} \quad A_i Y_i A_j = 0 \quad \text{for all } i \neq j,$$

follow if and only if the A_i are "disjoint". We may write (1.23) as

$$(1.25) \quad K'DYB = K'D = B$$

and (1.24) as

$$(1.26) \quad DYB = D.$$

When the A_i are disjoint, (1.8) holds and so (1.25) \Rightarrow (1.26) using the left-hand rank cancellation rule (Anderson and Styan, 1980, page 12, Lemma 2.2). Conversely (1.26) implies that $r(D) \leq r(B) = r(K'D) \leq r(D)$ and so (1.8) holds

and the A_i are "disjoint".

This result from Rao and Yanai (1979, page 5, Theorem 1) closely parallels the result of Takemura (1980, page 4, Proposition 2.3): that if $P = P^2$ and $C(P) = U = U_1 \oplus \dots \oplus U_k$, with U_1, \dots, U_k "independent" then $P = \sum_{i=1}^k P_i$, with

$$(1.27) \quad P_i^2 = P_i, \quad i = 1, \dots, k, \quad \text{and} \quad P_i P_j = 0 \quad \text{for all} \quad i \neq j,$$

and the P_i are unique. The correspondence between Takemura and Rao & Yanai is found by setting $P_i = A_i Y_i$; the assertion of uniqueness was not given by Rao & Yanai.

To prove Takemura's Proposition 2.3 let us write

$$(1.28) \quad P = BY = \sum_{i=1}^k A_i Y_i$$

for some generalized inverse $Y = B^-$, cf. (1.23), and Theorem 3 of Marsaglia and Styan (1974, page 273). Setting $P_i = A_i Y_i$ then shows that (1.24) \Rightarrow (1.27). The converse follows from $r(A_i) = \dim U_i = r(P_i) = r(A_i Y_i)$ and the right-hand rank cancellation rule Lemma 2.1 in Anderson and Styan (1980, page 12).

To see that the P_i are unique we write

$$(1.29) \quad P = BZ, \quad \text{where} \quad Z = B^-$$

not necessarily equal to Y . We may do this in view of Theorem 3 of Marsaglia and Styan (1974, page 273). When the A_i are "independent" then

$$(1.30) \quad P = K'DY = K'DZ \Rightarrow DY = DZ$$

using (1.8) and the left-hand rank cancellation rule, and so

$$(1.31) \quad DY = \begin{pmatrix} A_1 Y_1 \\ \vdots \\ A_k Y_k \end{pmatrix} = \begin{pmatrix} P_1 \\ \vdots \\ P_k \end{pmatrix}$$

is uniquely determined.

2. Projection and Idempotent Matrices.

The square matrix A is idempotent whenever $A^2 = A$; such a matrix is called a "projection matrix" by Takemura (1980, page 2). An interesting discussion of this terminology is given by Ben-Israel and Greville (1974, page 51, footnote).

Takemura's Proposition 2.1 closely parallels Corollary 11.2 of Marsaglia and Styan (1974, page 283). Since the null space

$$(2.1) \quad N(I - A) = \{x : (I-A)x = 0\} = \{x : Ax = x\}$$

it would seem more appropriate to replace (iii) and (iv), respectively, by

$$(iii)' \quad C(A) = N(I-A), \quad \text{and} \quad (iv)' \quad N(A) = C(I-A).$$

From (1.7) we see that

$$(v) \quad C(A) \text{ and } C(I-A) \text{ are "independent"} \iff r(A, I-A) = r(A) + r(I-A). \dots (v)'$$

Then it is obvious that $(i) \Leftrightarrow (ii)$ and that $(iii)' \Leftrightarrow (iv)'$, while $(i) \Leftrightarrow (v)'$ is $(5.15) \Leftrightarrow (5.21)$ in Corollary 11.2 of Marsaglia and Styan (1974, page 283), and $(i) \Leftrightarrow (iii)'$ is proved by Anderson and Styan (1980, pages 7-8, section 2.1).

Takemura's Proposition 2.2 (page 4) extends Theorem 1.1 of Anderson and Styan (1980, page 5). Let A_1, \dots, A_k be square matrices, not necessarily symmetric, and let $A = \sum_{i=1}^k A_i$. Consider the following statements

- (a) $A_i^2 = A_i, \quad i = 1, \dots, k,$
- (b) $A_i A_j = 0$ for all $i \neq j,$
- (c) $A^2 = A,$
- (d) $\sum_{i=1}^k r(A_i) = r(A),$
- (d1) $r(A_1, \dots, A_k) = \sum_{i=1}^k r(A_i),$
- (d2) $C(A_1, \dots, A_k) = C(A).$

Then Takemura's Proposition 2.2 is that

$$(a), (b) \Rightarrow (c), (d1), (d2).$$

In their (1.4), Anderson and Styan (1980, pages 5 and 11A) proved that

$$(a), (b) \Rightarrow (c), (d).$$

That $(d) \Rightarrow (d1)$ is $(6.1) \Rightarrow (6.2)$ in Theorem 13 of Marsaglia and Styan (1974, pages 284-285). That $(d1) \Rightarrow (d2)$ follows at once since $C(A_1, \dots, A_k)$ always contains $C(A)$, or equivalently $C(K'D) \supset C(K'DK)$.

Since $(a), (b) \Rightarrow (d1)$ Takemura (1980, page 5, lines -8 to -10) suggests that "it may well be justified to call projection matrices $A_i, i = 1, \dots, k,$

(linearly) independent if $A_i A_j = 0$ for all $i \neq j$." I think that this is not very wise since

(a), (d1) \nRightarrow (b);

i.e., "independent" projections A_1, \dots, A_k are not necessarily "pairwise orthogonal": $A_i A_j = 0$ for all $i \neq j$. For example with $k = 2$, let

$$(2.2) \quad A_1 = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}, \quad A_2 = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}.$$

Takemura's Proposition 2.3 (page 4) has been discussed already in this review (see page 7).

Takemura's Proposition 2.4 (page 6) is well known and can easily be proved without diagonalizability (I prefer using "diagonability" and will do so below), cf. e.g., Rao (1973, page 28 (i)).

3. Cochran-type Theorems.

Takemura's Lemma 3.1 (page 7) builds on his Proposition 2.2 to show that

$$(d) \iff (d1), (d2).$$

We have already shown that $(d) \Rightarrow (d1), (d2)$, cf. page 9 of this review. To go the other way let us write:

$$\begin{aligned} (d1) : \quad & r(K'D) = r(D) \\ (d2) : \quad & C(K'D) = C(K'DK) \\ (d) : \quad & r(K'DK) = r(D). \end{aligned}$$

Clearly $(d2) \Rightarrow r(K'D) = r(K'DK)$ and so $(d1), (d2) \Rightarrow (d)$.

Takemura's Theorem 3.2 (page 9) builds on Theorem 3.3 of Anderson and Styan (1980, page 24), but does not seem to be a "simpler (but equivalent) version". Let us write

$$\begin{aligned}
(a)_r : \quad & A_i^r = A_i, \quad i = 1, \dots, k, \\
(b) : \quad & A_i A_j = 0 \quad \text{for all } i \neq j, \\
(c)_r : \quad & A^r = A, \\
(d) : \quad & \sum_{i=1}^k r(A_i) = r(A), \\
(e2) : \quad & AA_i = A_i A, \quad i = 1, \dots, k.
\end{aligned}$$

The condition (e2) was used by Anderson and Styan (1980, page 18, Theorem 3.1).

Takemura's Theorem 3.2 then shows that

$$(a)_r, (b) \iff (c)_r, (d), (e2).$$

That

$$(a)_r, (b) \Rightarrow (c)_r, (d)$$

was proved by Anderson and Styan (1980, page 18, Theorem 3.1), while

$$(b) \Rightarrow (e2)$$

always holds. To go the other way, we note first that

$$(d), (e2) \Rightarrow (b).$$

This was proved for symmetric matrices by Luther (1965, page 684, Theorem 1) and for square matrices not necessarily symmetric by Marsaglia (1967, page 461, Theorem 3); see also Marsaglia and Styan (1974, page 286, Theorem 15(II)). Hence

$$(c)_r, (d), (e2) \Rightarrow (b), (c)_r \Rightarrow (a)_r, (b)$$

using (3.23) on page 25 of Anderson and Styan (1980). In their Theorem 3.3 Anderson and Styan (1980, page 24) proved that

$$(a)_r, (b) \Leftrightarrow (c)_r, (d), (e2)_r,$$

where

$$(e2)_r : A^{r-2} A_i = A_i A^{r-2}, \quad i = 1, \dots, k.$$

Since

$$(e2) \Rightarrow (e2)_r \quad \text{and} \quad (b) \Rightarrow (e2)$$

always hold, and since

$$(d), (e2) \Rightarrow (b)$$

(see page 12 above) it seems to me that Takemura's Theorem 3.2 is equivalent to the Anderson and Styan Theorem 3.3.

4. Matrix Polynomials.

Takemura's Theorem 3.3 (page 10) extends the Anderson and Styan Theorem 3.3 by replacing their (a) and (c) conditions by a matrix polynomial $P(\cdot)$ of degree at least 2. Let us write

$$\begin{aligned}
 (a)_{p0} &: P(A_i) = 0, & i = 1, \dots, k, \\
 (a)_{p1} &: A_i P(A_i) = 0, & i = 1, \dots, k, \\
 (b) &: A_i A_j = 0 & \text{for all } i \neq j, \\
 (c)_P &: P(A) = 0, \\
 (d) &: \sum_{i=1}^k r(A_i) = r(A), \\
 (e2) &: AA_i = A_i A, & i = 1, \dots, k.
 \end{aligned}$$

Takemura's Theorem 3.3 then shows that

$$(c)_P, (d), (e2) \Rightarrow (a)_P, (b),$$

where

$$(a)_P = \begin{cases} (a)_{p0} & \text{if } P(0) = 0, \\ (a)_{p1} & \text{if } P(0) \neq 0. \end{cases}$$

Since $(d), (e2) \Rightarrow (b)$ always holds, cf. page 12 above, Takemura's Theorem 3.3 reduces to

$$(4.1) \quad (b), (c)_P, (d) \Rightarrow (a)_P.$$

We strengthen (4.1) by showing that

$$(4.2) \quad (b), (c)_p, (d) \Rightarrow (a)_p^*,$$

where

$$(a)_p^* : P(A_i) = c(I - A^- A_i), \quad i = 1, \dots, k,$$

$P(0) = cI$, and A^- is a generalized inverse of A . Then $(a)_p^* \Rightarrow (a)_{p0}$ if $c = 0$.

To prove (4.2) we note that when (b) holds

$$(4.3) \quad A^p = \sum_{i=1}^k A_i^p$$

for any positive integer p , and so

$$(4.4) \quad P(A) = cI + \sum_{i=1}^k [P(A_i) - cI].$$

When (d) holds we may apply Theorem 1.2 of Anderson and Styan (1980, page 6) to find

$$(4.5) \quad A_i A^- A_i = A_i, \quad i = 1, \dots, k, \quad \text{and} \quad A_i A^- A_j = 0 \quad \text{for all } i \neq j.$$

Postmultiplying (4.4) by $A^- A_i$ and applying (4.5) yields

$$(4.6) \quad [P(A)] A^- A_i = c A^- A_i + [P(A_i) - cI], \quad i = 1, \dots, k,$$

and so $(c)_p \Rightarrow (a)_p^*$. Premultiplying $(a)_p^*$ by A_i yields $(a)_{p1}$.

Takemura's Lemma 4.1 (page 14) shows that if $P(x) = 0$ has no multiple root and if $(c)_P: P(A) = 0$ holds, then A is diagonalizable. Since (by definition) the minimal polynomial must divide $P(A)$ it follows that when $P(A)$ has no multiple root then neither does the minimal polynomial $\phi(A)$. This characterizes diagonalizability of the matrix A , cf. Mirsky (1955, page 297, Theorem 10.2.5), and so the condition in Lemma 4.1 does not seem to be as strong as Takemura claims on page 13 (line -1).

Takemura's Theorem 4.1 is not new. It contains his Lemma 4.1 and the decomposition into "independent projections", more usually known as "principal idempotents" (cf. Ben-Israel and Greville, 1974, pages 52-55, especially Theorem 9 and Exercise 27).

To Takemura's Corollary 4.1 should be added $\sum_{j=1}^r H_j = I$.

Takemura's Theorem 4.2 (pages 15-16) considers a polynomial $P(x)$ with no multiple root and then extends his Theorem 3.3 to show that

$$(c)_P, (d), (e2) \Rightarrow A_i = \sum_{j=1}^{\ell} \lambda_j H_{ij},$$

where $\lambda_1, \dots, \lambda_{\ell}$ are the nonzero characteristic roots of A and the H_{ij} are "independent projections" (principal idempotents). In fact $H_{ij}H_{i',j'} = 0$ whenever $i \neq i'$ and/or $j \neq j'$. The condition that $P(x)$ has no multiple root assures that $(c)_P \Rightarrow A$ diagonalizable. Since $(d), (e2) \Rightarrow (b)$ we see the interesting result (essentially Takemura's Theorem 4.4, page 21) that

$$(4.7) \quad A \text{ diagonalizable}, (b), (d) \Rightarrow A_i \text{ diagonalizable}, i = 1, \dots, k.$$

[We must still include (d) in (4.7) since (b) \nRightarrow (d) in general; however (b) always implies (e2).]

We may extend (4.7) by noting that a matrix A is diagonalizable if and only if all its characteristic roots are regular (cf. Mirsky, 1955, page 294, Theorem 10.2.3). The characteristic root λ of the matrix A is said to be regular whenever its geometric and algebraic multiplicities are equal (cf. Mirsky, 1955, page 294, Definition 10.2.1). The algebraic multiplicity of λ is the multiplicity of λ as a root of the characteristic equation; the geometric multiplicity is the nullity of the matrix $A - \lambda I$.

Let A be $n \times n$ of rank r , and let A_i have rank r_i , $i = 1, \dots, k$. Let $\lambda_1, \dots, \lambda_\ell$ be the nonzero characteristic roots of A . Let m_{ij} be the algebraic multiplicity and g_{ij} the geometric multiplicity of λ_j as a characteristic root of A_i , so that, cf. Mirsky (1955, page 214, Theorem 7.6.1),

$$(4.8) \quad n \geq m_{ij} \geq g_{ij} \geq 0; \quad i = 1, \dots, k, \quad j = 1, \dots, \ell.$$

Let m_{0j} be the algebraic multiplicity and g_{0j} the geometric multiplicity of λ_j as a characteristic root of A . Then

$$(4.9) \quad n \geq m_{0j} \geq g_{0j} \geq 1; \quad j = 1, \dots, \ell.$$

Let m_{i0} be the algebraic multiplicity and g_{i0} the geometric multiplicity of 0 as a characteristic root of A_i , $i = 1, \dots, k$. Then

$$(4.10) \quad m_{i0} = n - m_i = n - \sum_{j=1}^{\ell} m_{ij}, \quad i = 1, \dots, k,$$

$$(4.11) \quad g_{i0} = n - r_i = n - \text{rank}(A_i), \quad i = 1, \dots, k.$$

Hence

$$(4.12) \quad n \geq r_i \geq m_{i.} \geq 0; \quad i = 1, \dots, k.$$

Let m_{00} be the algebraic multiplicity and let g_{00} be the geometric multiplicity of 0 as a characteristic root of A. Then

$$(4.13) \quad m_{00} = n - m_{0.} = n - \sum_{j=1}^{\ell} m_{0j},$$

$$(4.14) \quad g_{00} = n - r = n - \text{rank}(A).$$

Hence

$$(4.15) \quad n \geq r \geq m_{0.} \geq 0.$$

Let

$$(4.16) \quad A_i = B_i C_i', \quad i = 1, \dots, k,$$

be full rank decompositions, so that B_i and C_i are both $n \times r_i$ of rank r_i .

Then

$$(4.17) \quad A = \sum_1^k A_i = \sum_1^k B_i C_i' = BC',$$

where

$$(4.18) \quad B = (B_1, \dots, B_k) \quad \text{and} \quad C = (C_1, \dots, C_k)$$

are both $n \times \sum_1^k r_i$.

Now suppose that

$$(b) \quad A_i A_j = 0 \quad \text{for all } i \neq j$$

holds. Then $C'_i B_j = 0$ for all $i \neq j$ and so

$$(4.19) \quad C'B = \begin{pmatrix} C'_1 B_1 & & \\ & \ddots & \\ & & C'_k B_k \end{pmatrix} = C'_1 B_1 \oplus \dots \oplus C'_k B_k,$$

the direct sum of the $C'_i B_i$.

Let $\text{am}_j(A)$ denote the algebraic multiplicity and let $\text{gm}_j(A)$ denote the geometric multiplicity of λ_j as a characteristic root of A . Then using the fact that the matrices FG and GF have the same nonzero characteristic roots (cf. Mirsky, 1955, page 200, Theorem 7.2.3), we may write for $j = 1, \dots, \ell$

$$(4.20) \quad m_{0j} = \text{am}_j(A) = \text{am}_j(BC') = \text{am}_j(C'B) = \sum_{i=1}^k \text{am}_j(C'_i B_i) \\ = \sum_{i=1}^k \text{am}_j(B_i C'_i) = \sum_{i=1}^k m_{ij},$$

while

$$(4.21) \quad m_0 = \sum_{j=1}^{\ell} m_{0j} = \sum_{i=1}^k \sum_{j=1}^{\ell} m_{ij} = \sum_{i=1}^k m_i.$$

so that

$$(4.22) \quad n - \text{am}_0(A) = \sum_{i=1}^k [n - \text{am}_0(A_i)].$$

We now use the result that the matrices $FG - I$ and $GF - I$ have the same nullity, cf. Ouellette (1981, equation (4.147)). Let $v(\cdot)$ denote nullity. Then for each $j = 1, \dots, \ell$

$$\begin{aligned}
 (4.23) \quad g_{0j} &= g_{mj}(A) = v(A - \lambda_j I) = v(BC' - \lambda_j I) = v(C'B - \lambda_j I) \\
 &= \sum_{i=1}^k v(C_i' B_i - \lambda_j I_{r_i}) = \sum_{i=1}^k v(B_i C_i' - \lambda_j I_n) \\
 &= \sum_{i=1}^k v(A_i - \lambda_j I_n) = \sum_{i=1}^k g_{ij}.
 \end{aligned}$$

Hence when (b) holds all the nonzero characteristic roots of the A_i , $i = 1, \dots, k$, must be characteristic roots of A , and all the nonzero characteristic roots of A must be characteristic roots of A_i for some i .

Furthermore, since $g_{ij} \leq m_{ij}$ from (4.8) we obtain

$$(4.24) \quad g_{0j} = \sum_{i=1}^k g_{ij} \leq \sum_{i=1}^k m_{ij} = m_{0j}; \quad j = 1, \dots, \ell,$$

and so for each $j = 1, \dots, \ell$

$$(4.25) \quad g_{0j} = m_{0j} \Rightarrow g_{ij} = m_{ij}; \quad i = 1, \dots, k.$$

Thus if λ_j is a regular nonzero characteristic root of A then when (b) holds λ_j is also a regular characteristic root[†] of each A_i , $i = 1, \dots, k$. This does not, however, hold true for the 0 characteristic root of A , for if $k=2$ and

[†] Notice that $g_{ij} = 0 \iff m_{ij} = 0$; we will then speak of λ_j as a regular characteristic root of A_i even though A_i does not have λ_j as a root.

$$(4.26) \quad A_1 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad \text{and} \quad A_2 = \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix}$$

then (b) holds and $A = 0$ so 0 is a regular characteristic root of A , but 0 is clearly not a regular characteristic root of either A_1 or of A_2 . The equation (4.23) is no longer valid when $\lambda_j = 0$ since the matrices FG and GF do not necessarily have the same nullity (or rank). However

$$(4.27) \quad n - \text{gm}_0(A) = r \leq \sum_1^k r_i = \sum_1^k [n - \text{gm}_0(A_i)].$$

Now suppose that in addition

$$(d) \quad \sum_1^k r(A_i) = r(A)$$

holds. Substitution in (4.27) then yields

$$(4.28) \quad n - \text{gm}_0(A) = \sum_1^k [n - \text{gm}_0(A_i)]$$

and so

$$(4.29) \quad \begin{aligned} \text{gm}_0(A) &= n - \sum_1^k [n - \text{gm}_0(A_i)] \\ &\leq n - \sum_1^k [n - \text{am}_0(A_i)] = n - \sum_1^k m_i = n - m_0. \end{aligned}$$

Hence if 0 is a regular characteristic root of A then 0 must be a regular characteristic root of A_i , for all $i = 1, \dots, k$. We have, therefore, proved the following stronger version of Takemura's Theorems 4.2 and 4.4 and our (4.7).

THEOREM 4.1. Let A_1, \dots, A_k be $n \times n$ matrices, not necessarily symmetric, and let $A = \sum_{i=1}^k A_i$. Suppose that

$$(b) \quad A_i A_j = 0 \quad \text{for all } i \neq j.$$

Then the set of nonzero characteristic roots of A coincides with the set of all the nonzero characteristic roots of all the A_i , $i = 1, \dots, k$. Furthermore, the nonzero characteristic root λ of A is regular if and only if λ is a regular nonzero characteristic root of each A_i , $i = 1, \dots, k$.

If, in addition,

$$(d) \quad \sum_{i=1}^k \text{rank}(A_i) = \text{rank}(A),$$

then the characteristic root 0 of A is regular if and only if 0 is a regular characteristic root of each A_i , $i = 1, \dots, k$. Equivalently,

$$(4.30) \quad \text{rank}(A^2) = \text{rank}(A) \iff \text{rank}(A_i^2) = \text{rank}(A_i), \quad i = 1, \dots, k.$$

Mäkeläinen and Styan (1976, Lemma 2) have shown that the zero characteristic root of a matrix A is regular if and only if $r(A^2) = r(A)$. Such a matrix A is said to have index 1, cf. Ben-Israel and Greville (1974, page 169). A direct proof of (4.30) goes as follows. Let

$$(4.31) \quad D = A_1 \oplus \dots \oplus A_k \quad \text{and} \quad K = (I, \dots, I)',$$

cf. (1.3) and (1.4) on page 2. Then under (b) $DKK'D = D^2$ so that $A^2 = K'D^2K$, while (d) yields

$$(4.32) \quad r(D) = r(K'DK) = r(K'D) = r(DK)$$

using Sylvester's Law of Nullity, cf. Anderson and Styan (1980, page 11A). Thus under (b) and (d) the result (4.30) becomes

$$(4.33) \quad r(K'D^2K) = r(D)$$

if and only if

$$(4.34) \quad r(D^2) = r(D).$$

That (4.33) \Rightarrow (4.34) follows at once from $r(K'D^2K) \leq r(D^2) \leq r(D)$. To go the other way suppose that (4.34) holds. Then using (4.32) and the rank cancellation rules (2.10) and (2.11) in Theorem 2 of Marsaglia and Styan (1974, page 271), we obtain $r(K'D^2K) = r(D^2K) = r(D^2)$, and so (4.34) \Rightarrow (4.33).

We see also that if (b) and (d) hold then for any positive integer p (4.32) implies that $r(K'D^pK) = r(D^p)$ and so we have proved that

THEOREM 4.2. *Let the $n \times n$ matrices A_1, \dots, A_k and A be defined as in Theorem 4.1 and suppose that both (b) and (d) hold. Then for any positive integer p*

$$(4.35) \quad \sum_1^k \text{rank}(A_i^p) = \text{rank} \left(\sum_1^k A_i^p \right).$$

Takemura's Theorem 4.3 (page 16) is well known; for a nice proof see Mirsky (1955, page 318, Theorem 10.6.3).

We may strengthen Takemura's Corollary 4.2 (page 20) by allowing the polynomial $P(x)$ to possibly have multiple roots and by not requiring that $P(0) = 0$. Instead then let $P(0) = cI$ as on page 15 of this review. Thus from (4.3) we find that if $P(A_i) = 0$, $i = 1, \dots, k$, then under (b) \equiv (i)

$$(4.36) \quad P(A) = -(k-1)cI.$$

Since (b) always implies (e2) \equiv (iv), it remains to consider when does (b) imply (d) \equiv (v). That (b) $\not\Rightarrow$ (d) in general has already been noted (top of page 17 of this review; see also Anderson and Styan (1980, page 5)). Takemura's Corollary 4.2 shows that

$$(4.37) \quad (b) \text{ and } A_i \text{ diagonable, } i = 1, \dots, k \Rightarrow (d).$$

This result, however, is implied by

$$(4.38) \quad (b) \text{ and } \text{rank}(A_i^2) = \text{rank}(A_i), \quad i = 1, \dots, k \Rightarrow (d),$$

which was proved by Marsaglia and Styan (1974, page 286, Theorem 15(I)). We recall that $\text{rank}(A_i^2) = \text{rank}(A_i)$ means that the zero characteristic root of A_i is regular, while A_i diagonable means that all the characteristic roots are regular, cf. pages 17 and 22 of this review.

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